

# Marshall Space Flight Center

- Huntsville, Alabama
- 6,000 Civil Servants & Contractors
- Located on Redstone Arsenal
- ► NASA's Propulsion Center
- Currently Building the Space Launch System (SLS)



### NASA Internship Programs

- ▶ 200 + Marshall Interns
- ▶ 3 Academies
- ▶ 30 Academy Inters
- Space Hardware and Robotics Academy – 4 Project Groups
- Propulsion Academy –3 Project Groups
- Leadership AcademySingle Inter Projects



### NASA Leadership Academy

- Single Intern Research Projects
- Weekly NASA Director Chats
- Weekly Team Building Activities
- Trips to NASA Centers



#### **NASA Centers and Installations**



# NASA Leadership Academy Trips

## Michoud Assembly Facility

- New Orleans, Louisiana
- 43+ acre Manufacturing Building
- Manufactured Flight Hardware



### Goddard Space Flight Center

- Greenbelt, Maryland
- 10,000 Civil Servants & Contractors
- James Webb Space Telescope (JWST)
- Transiting Exoplanet Survey Satellite (TESS)
- Satellite Servicing Project



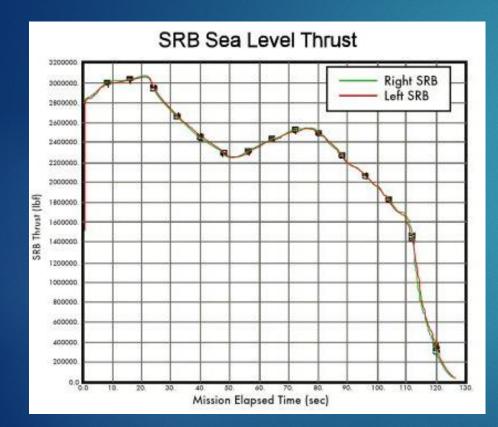
### NASA Headquarters

- Science Mission Director
- Human Exploration and Operations Mission Director
- Space Technology Mission Director
- Aeronautics Research Mission Director





# Background





#### Dynamic Pressure

Glenn Research Center

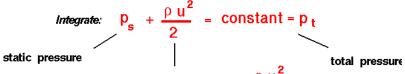


p = pressure

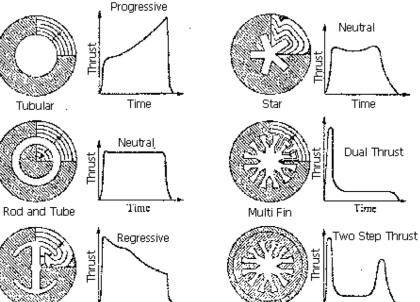
 $\rho$  = density

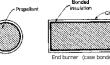
u = velocity

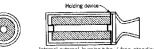
Collect:  $\frac{d}{dx} (p + \frac{\rho u^2}{2}) = 0$ 

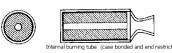


dynamic pressure =  $q = \frac{\rho u^2}{2}$ 



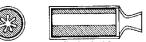




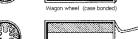


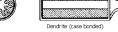


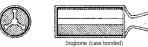


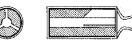






















Time

Double Anchor

**Dual Composition** 

Time

#### **Launch Abort System Configuration**

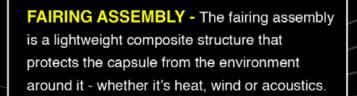
The Launch Abort System, or LAS, is positioned atop the Orion crew module. It is designed to protect astronauts if a problem arises during launch by pulling the spacecraft away from a failing rocket. Weighing approximately 16,000 pounds, the LAS can activate within milliseconds to pull the vehicle to safety and position the module for a safe landing. The LAS is comprised of three solid propellant rocket motors: the abort motor, an attitude control motor, and a jettison motor.

**JETTISON MOTOR** - The jettison motor will pull the LAS away from the crew module, allowing Orion's parachutes to deploy and the spacecraft to safely land in the Ocean.

#### **ATTITUDE CONTROL MOTOR -**

The attitude control motor consists of a solid propellant gas generator with eight proportional valves equally spaced around the outside of the three-foot diameter motor. The motor can exert up to 7,000 pounds of steering force to the vehicle in any direction upon command from the Orion crew module.

ABORT MOTOR - The abort motor is capable of producing about 400,000 pounds of thrust to quickly pull the crew module away from danger if problems develop on the launch pad or during the ascent.



# Launch Abort System

- Abort Motor
- Attitude Control Motor
- Jettison Motor
- Parachutes



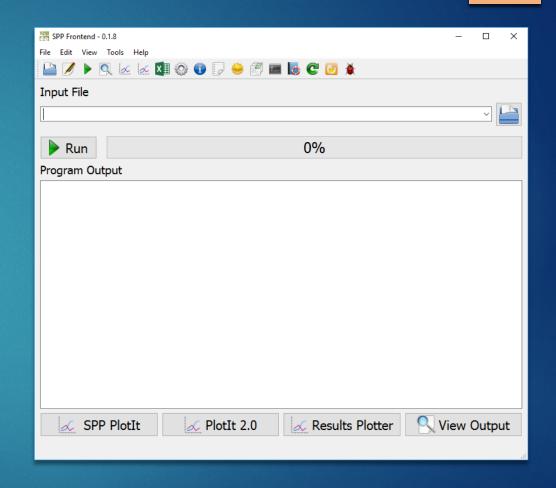


### Solid Performance Program (SPP)

- ► Fortran based software
- ▶ 40+ years of development
- ► Shorter runtime

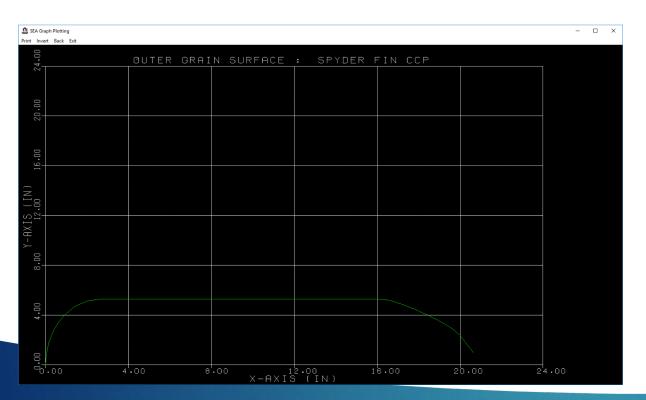


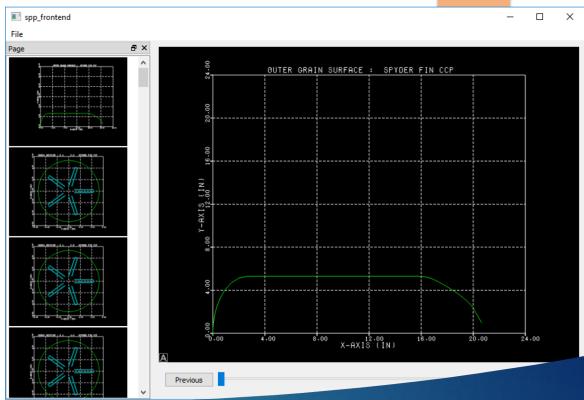
```
! Whether P(1) is in psia or the default, atm
NAMELISTS
   ! - P(1) ~ Pc Avg from AVE BAL.LIS for Isp parity w/ & w/o BALIS
   ! Whether P(1) is in psia or the default, atm
                                   A=1.09E18, N=1., B=0.0, JENSEN/JONES(1978)
A=1.45E22, N=2., B=0.0, JENSEN/JONES(1978)
A=3.22E22, N=2., B=0.0, JENSEN/JONES(1978)
A=3.0E16, N=0.5, B=4.37, JENSEN/JONES(1978)
A=3.0E16, N=0.5, B=0.0, ESTIMATE
H+CL=HCL.
END TBR REAX
                                   A=1.30E13, N=0.0, B=2.087, JENSEN/JONES(1978)
A=5.E11, N=-0.5, B=5.673, ESTIMATE
ALO+HCL=ALOCL+H.
                                   A=1.E11, N=-0.5, B=5.619, ESTIMATE
A=1.E11, N=-0.5, B=5.627, ESTIMATE
ALCL+OH=ALOCL+H,
ALOH+OH=H+ALO2H,
LAST REAX
THIRD BODY REAX RATE RATIOS
ALL EQUAL 1.0
   ! Outputs at throat and ASUP area ratios (unless overridden by ARPRNT)
   !Propellant Boundary
    ! Axial Propellant Boundary
    ! - Must be monotonically increasing
   xpb = 0.0, 0.005, 0.030, 0.180, 0.150, 0.250, 0.400, 0.600, 0.900, 1.400, 2.000, 2.650, 15.800, 16.327, 16.541, 16.834, 17.050, 17.240, 17.422, 17.599, 17.771, 17.938, 18.100, 18.257, 18.409, 18.556, 18.698, 18.835, 19.014, 19.275, 19.514, 19.682, 19.968, 20.632,
  rpb = 0.000, 0.325, 0.795, 1.292, 1.758, 2.247, 2.800, 3.359, 3.980, 4.673, 5.128, 5.300, 5.300, 5.241, 5.183, 5.066, 4.949, 4.831, 4.714, 4.597, 4.480, 4.363, 4.246, 4.128, 4.011, 3.894, 3.777, 3.660, 3.500, 3.250, 3.000, 2.808, 2.414, 1.000,
    ! Number of points in PB, RPB (NXR <= 350)
    ! Grain Design Plotting
    ! To re-run a previously calculated geometry (bypassing GDM module):
```



# Input File

# Existing Frontend GUI

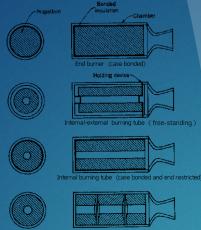




# SPP Plotting Tool

# Existing Tool

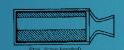
### Results



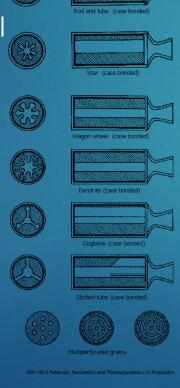
Multiple plotting tools

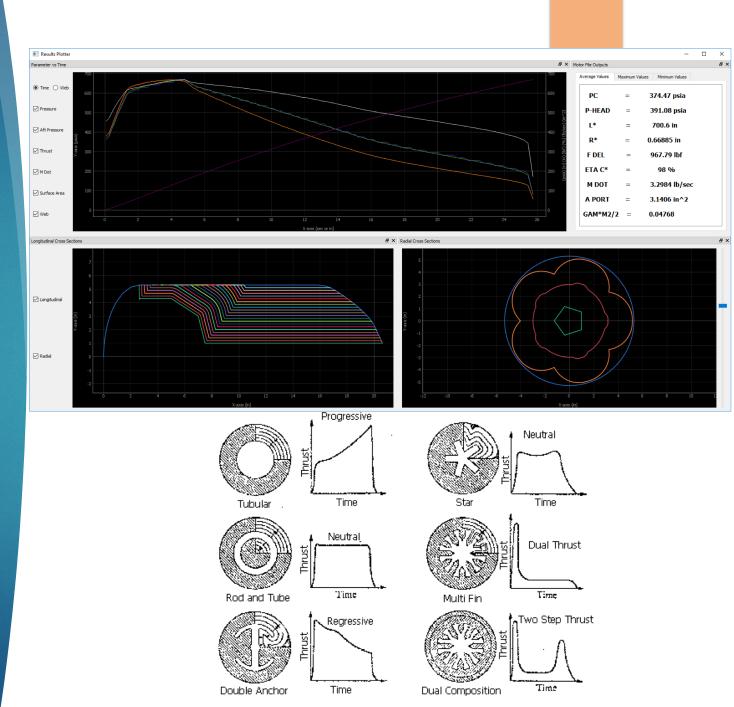


Radial and Longitudinal



Displays motor results





# Acknowledgements

I would like to thank Brett Ables, Ben Gauvain, Todd Steadman, Charlie Martin, Tim Kibbey, Sadie Boyle, and Bobby Taylor for their mentorship, and The Oregon Space Grant for sponsoring this opportunity.

# Questions?